

DOING PHYSICS WITH MATLAB

MATHEMATICAL ROUTINES

COMPUTATION OF ONE-DIMENSIONAL INTEGRALS

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math_1d_integration.m

mscript to evaluate the integral

$$\int_a^b f(x) dx$$

using Simpson's 1/3 rule

simpson1d.m

Function used to estimate of the integral using Simpson's 1/3 rule

NUMERICAL INTEGRATION COMPUTATION OF ONE-DIMENSIONAL INTEGRALS

The function `simpson1d.m` is a very versatile , accurate and easy to implement function that can be used to evaluate a definite integral of a function between a lower bound and an upper bound. It is easier to use than the standard Matlab integration functions such as `quad`. The function `simpson1d.m` is described in detail below.

[View more detailed notes on a numerical approach to integration](#)

Simpson's 1/3 rule

This rule is based on using a quadratic polynomial approximation to the function $f(x)$ over a pair of partitions. $N-1$ is the number of partitions where N must be **odd** and $h = (b - a) / (N-1)$. The integral is expressed below and is known as *composite Simpson's 1/3 rule*.

$$I = \frac{h}{3} \{ (f_1 + f_N + 4(f_2 + f_4 + \dots + f_{N-2}) + 2(f_3 + f_5 + \dots + f_{N-1})) \}$$

Simpson's rule can be written vector form as

$$I = \frac{h}{3} \mathbf{c} \mathbf{f}^T$$

where $\mathbf{c} = [1 \ 4 \ 2 \ 4 \ \dots \ 2 \ 4 \ 1]$ and $\mathbf{f} = [f_1 \ f_2 \ \dots \ f_N]$.

Simpson's rule is an example of a *closed Newton's-Cotes* formula for integration. Other examples can be obtained by fitting higher degree polynomials through the appropriate number of points. In general we fit a polynomial of degree N through $N + 1$ points. The resulting polynomials can then be integrated to provide an integration formula. Because of the lurking oscillations associated with the Gibbs effect, higher-order formulas are not used for practical integration.

simpson1d.m

The function f and the lower bound a and the upper bound b are passed onto the function (in the order f, a, b) and the function returns the value of the integral

```
function integral = simpson1d(f,a,b)

% [1D] integration - Simpson's 1/3 rule
%     f function      a = lower bound      b = upper bound
%     Must have odd number of data points
%     Simpson's coefficients  1 4 2 4 ... 2 4 1

numS = length(f);           % number of data points

sc = 2*ones(numS,1);
sc(2:2:numS-1) = 4;
sc(1) = 1; sc(numS) = 1;

h = (b-a)/(numS-1);

integral = (h/3) * f * sc;
```

math_1d_integration.m

You need to modify the mscript to evaluate the integral of your function.
Input parameters to define the function

N	number of partitions (must be an odd number)
a	lower bound of integral
b	upper bound of integral
y	function to be integrated
tx	title for X-axis
ty	title for Y-axis

The mscript outputs the value of the integral in the Command Window. A graph of the function is plotted in a Figure Window.

```

clear all
close all
clc
format long

% INPUTS
=====

% Number of partitions
N = 9999;
% Lower bound
a = -4;
% Upper bound
b = 4;

x = linspace(a,b,N);
% Function to be integrated
y = -4.*x.^4 + 20.*x.^3 - 40.*x.^2 - 320.*x + 1664;

% X and Y label for graph axes
tx = 'x';
ty = 'y';

% OUTPUTS
=====

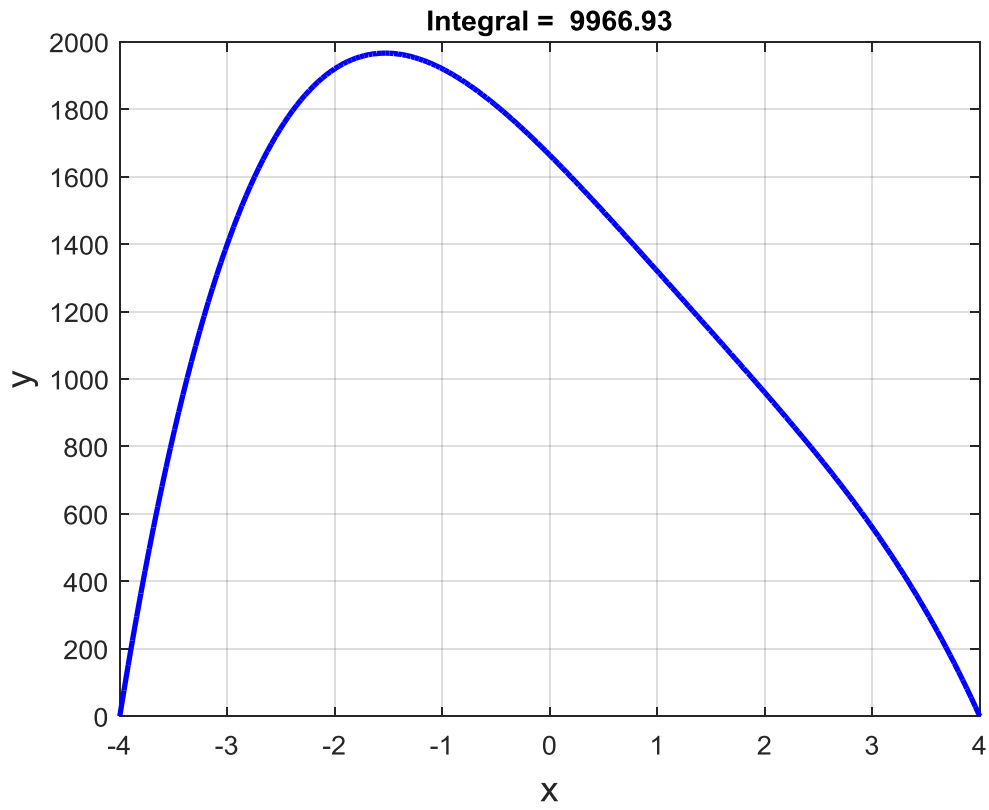
% Simpson's 1/3 rule -----
Integral = simpson1d(y,a,b);

disp(' ');
format long
disp('Integral = ');
disp(Integral);

% title
t1 = 'Integral = ';
t2 = num2str(Integral,6);
tm = [t1 t2];

% Graphics -----
figure(1)
fs = 14;
plot(x,y,'b','linewidth',2);
xlabel(tx,'fontsize',fs); ylabel(ty,'fontsize',fs);
title(tm);
box on;
grid on;

```



Integral =
9.966933333333331e+03